

26 juni 2006

1/8

Problem 1

- a) The two quantum point particles can each move in 3 spatial dimensions \Rightarrow 6 degrees of freedom

Note 1) We assume here point particles. If it are not

point particles, each particle has also 3 rotational degrees of freedom. More complex particles, like atoms, also have internal degrees of freedom.

- 2) For particle 1 in x -direction, there is the operator \hat{x}_1 for position, and \hat{p}_{x1} for momentum, but it is only 1 degree of freedom. Not 2?

- b) Pairs that do not commute:

$$\begin{cases} [\hat{x}_1, \hat{p}_{x1}] = i\hbar \\ [\hat{y}_1, \hat{p}_{y1}] = i\hbar \\ [\hat{z}_1, \hat{p}_{z1}] = i\hbar \\ [\hat{x}_2, \hat{p}_{x2}] = i\hbar \\ [\hat{y}_2, \hat{p}_{y2}] = i\hbar \\ [\hat{z}_2, \hat{p}_{z2}] = i\hbar \end{cases}$$

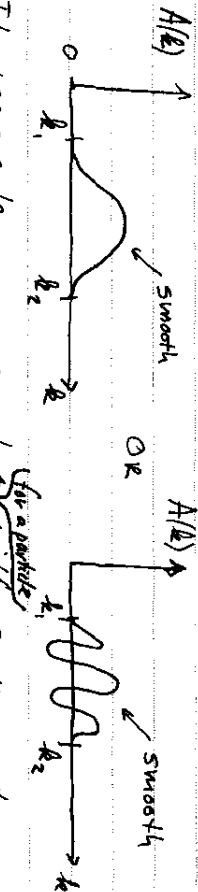
All other paired combinations of the 12 mentioned operators do commute, and have here five for example $[\hat{x}_1, \hat{p}_{y1}] = 0$, $[\hat{x}_1, \hat{z}_1] = 0$ and $[\hat{x}_1, \hat{x}_2] = 0$.

This can be understood by considering that any observable of particle 1, and any observable of particle 2 can be measured simultaneously with unlimited accuracy. The same holds for observables of the same particle but for different spatial directions.

Problem 2

2/8

- a) The state is a superposition of plane waves $e^{i(kx - \omega t)}$, each with a particular amplitude $A(k)$. The superposition only contains plane waves with a wave number k in the range $k_1 < k < k_2$, as for example



It represents a wave packet with a momentum of about $\langle p_x \rangle \approx \hbar k_0$, and a quantum uncertainty in momentum $\Delta p_x \approx \hbar \Delta k \approx \hbar \frac{k_2 - k_1}{2}$.

- b) The phase velocity is the propagation speed of each argument with a constant phase ($kx - \omega t$) for each plane wave (with its particular k) \Rightarrow $kx - \omega t$ is constant $\Rightarrow \frac{dx}{dt} = v_{\text{phase}} = \frac{\omega}{k}$ ($\omega > 0$)

- c) Here we consider a mechanical, massive free particle. The Hamiltonian is therefore

$$H = \frac{\hat{p}_x^2}{2m} = \frac{\hbar^2 k^2}{2m} \Rightarrow \text{the energy is } \frac{\hbar^2 k^2}{2m}$$

for a plane wave with wave number k , and the time evolution of such a plane wave is then a factor $e^{-iHt/\hbar} \Rightarrow$ gives $e^{-i \frac{\hbar^2 k^2}{2m} t}$ for a plane wave with certain k .

This can be used to define

$$\hbar \omega = \frac{\hbar^2 k^2}{2m} \Rightarrow \omega = \frac{\hbar k^2}{2m}$$

(the so-called dispersion relation)

d) The group velocity is $v_{group} = \frac{\partial \omega}{\partial k} \Rightarrow$

$$v_{group} = 2 \frac{\hbar k}{2m} \text{ . This should be evaluated}$$

for the k -values that are typical (most present)

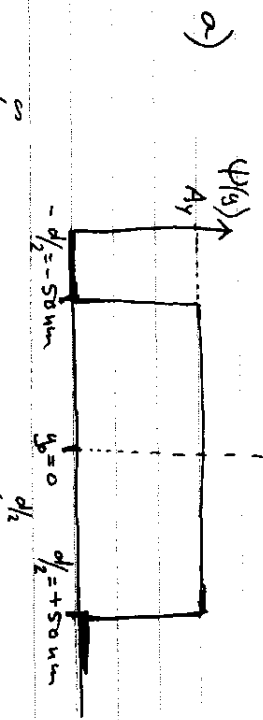
in the wave packet described by $A(k)$ \Rightarrow

$$\text{For this state } v_{group} \approx \frac{\hbar \left(\frac{k_0 \pm \Delta k}{2} \right)}{m} \approx \langle p_x \rangle$$

It is the propagation speed of the wave packet

Problem 3

a)



$$\int_{-\infty}^{\infty} |\psi(y)|^2 dy = 1 \Rightarrow \int_{-d/2}^{d/2} A_y^2 dy = 1 \Rightarrow A_y^2 \cdot d = 1$$

$$\Rightarrow A_y = \sqrt{\frac{1}{d}} = \sqrt{\frac{1}{100 \text{ nm}}} \approx 3.16 \cdot 10^3 \text{ m}^{-1/2}$$

b) $\bar{\psi}(k_y) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \psi(y) e^{-ik_y y} dy$

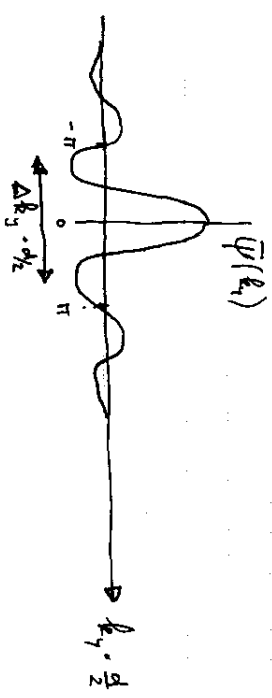
$$= \frac{1}{\sqrt{2\pi}} \int_{-d/2}^{d/2} A_y e^{-ik_y y} dy = \frac{1}{\sqrt{2\pi}} [A_y e^{-ik_y y}]_{-d/2}^{d/2}$$

$$= \frac{2 A_y}{\sqrt{2\pi}} \frac{\sin\left(\frac{d}{2} k_y\right)}{k_y} = \frac{d A_y}{\sqrt{2\pi}} \frac{\sin\left(\frac{d}{2} k_y\right)}{\frac{d}{2} k_y}$$

c) The answer on b) is a sinc function, which is centered around $k_y = 0$, and which

decreases in amplitude over a range

$$\frac{1}{2} \Delta k_y \approx \frac{2\pi}{d} \Rightarrow \Delta k_y \approx \frac{2\pi}{d} \Rightarrow \Delta p_y \approx \frac{2\pi \hbar}{d} \approx \frac{h}{\frac{d}{2}}$$



(5/8)

d) After the screen, the electron is a free particle. For a free particle, the momentum properties do not change in time $\Rightarrow \Delta p_y$ stays constant with time.

Note: this can for example be seen from:

Hamiltonian for the dynamics in y-direction is

$$\hat{H}_y = \frac{\hat{p}_y^2}{2m}$$

$\Delta p_y = \sqrt{\langle \hat{p}_y^2 \rangle - \langle \hat{p}_y \rangle^2}$, so we should look at

$$\frac{d \langle \hat{p}_y \rangle}{dt} = \frac{i}{\hbar} \langle \psi | [\hat{H}_y, \hat{p}_y] | \psi \rangle = 0 \text{ since } [\hat{H}_y, \hat{p}_y] = 0$$

and the same for $\frac{d \langle \hat{p}_y^2 \rangle}{dt} \Rightarrow = 0$

e) From question c) and d) we have

$\Delta p_y \approx \frac{\hbar}{d}$, and that it stays constant in time.

Consequently, a well-localized particle (in y-direction)

will become delocalized according to

$$W \approx \Delta y \approx \frac{\Delta p_y}{m} \cdot t_r \Rightarrow$$

$$W \approx \frac{\hbar \cdot t_r}{d \cdot m} \text{ as soon as } W \gg d$$

(the relation does not hold yet at times short after passing the screen when $\frac{\hbar t}{d \cdot m} \lesssim d$)

(6/8)

$$f) \bar{\Psi}(y) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \Psi(y) e^{-ik_y y} dy$$

$$= \frac{1}{\sqrt{2\pi}} \int_{y-d/2}^{y+d/2} A_y e^{-ik_y y} dy = \frac{1}{\sqrt{2\pi}} [A_y e^{-ik_y y}]_{y-d/2}^{y+d/2}$$

$$= \frac{d A_y}{\sqrt{2\pi}} \frac{\sin(\frac{d}{2} k_y)}{\frac{d}{2} d y} \cdot e^{-ik_y y}$$

phase shift of the state in k_y -representation as compared to b)

A shift in real space (y-direction) gives a global phase shift for the state in k_y -representation. \Rightarrow It does not give

any observable changes when measuring \hat{p}_y properties.

Problem 4

(7/8)

a) The energy eigenvalues are the solutions of the time-independent Schrödinger equation

$$\hat{H}_0 |\varphi_i\rangle = E_i |\varphi_i\rangle$$

In matrix notation this gives

$$\begin{pmatrix} E_0 & 0 \\ 0 & E_0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = E_0 \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} E_0 & 0 \\ 0 & E_0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = E_0 \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

Indeed two constant solutions for E_0 and $1/2 E_0$.

A two-state system (and a 2x2 Hamiltonian matrix) has at most 2 different eigenvalues, and 2 eigenvalues.

b) The two ^{energy} eigenvalues have the same eigenvalue $E_0 \Rightarrow E_0$ is two-fold degenerate.

c) Now consistent solutions (again two solutions) of $\hat{H}_1 |\varphi_i\rangle = E_i |\varphi_i\rangle$ are

$$\begin{pmatrix} E_0 & T \\ T & E_0 \end{pmatrix} \begin{pmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{pmatrix} = (E_0 + T) \begin{pmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{pmatrix}$$

$|\varphi_1\rangle$ \nearrow eigenvalue $1/4 E_0$

$$\begin{pmatrix} E_0 & T \\ T & E_0 \end{pmatrix} \begin{pmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{pmatrix} = (E_0 - T) \begin{pmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{pmatrix}$$

$|\varphi_2\rangle$ \nearrow eigenvalue $3/4 E_0$

d) See c), eigenvalues are

$E_0 + T$ (excited state, since $T > 0$)

$E_0 - T$ (ground state)

(8/8)

e) Normalized if $\langle \varphi_i | \varphi_i \rangle = 1 \Rightarrow$

$$\frac{1}{\sqrt{2}} (\langle \varphi_L | + \langle \varphi_R |) \cdot (\langle \varphi_L | + \langle \varphi_R |) \cdot \frac{1}{\sqrt{2}} = \frac{1}{2} (\langle \varphi_L | \varphi_L \rangle + \langle \varphi_R | \varphi_R \rangle + \langle \varphi_L | \varphi_R \rangle + \langle \varphi_R | \varphi_L \rangle)$$

with $\langle \varphi_L | \varphi_L \rangle = \langle \varphi_R | \varphi_R \rangle = 1$ and

$$\langle \varphi_L | \varphi_R \rangle = \langle \varphi_R | \varphi_L \rangle = 0 \quad \text{since}$$

$|\varphi_L\rangle$ and $|\varphi_R\rangle$ are orthonormal eigenvectors of $\hat{H}_0 \Rightarrow \langle \varphi_L | \varphi_L \rangle = 1$

f) The system is the no longer in an energy eigen state of the Hamiltonian \Rightarrow The expectation value for the observable that describes the position (which must commute with \hat{H}_0) will oscillate in time \Rightarrow The position of the electron oscillates between the two wells.

g) System is then again in an eigen state of the Hamiltonian \Rightarrow Is a stationary state \Rightarrow No expectation value of any observable depends on time. The system in and stays in the ground state $|\varphi_1\rangle = \frac{1}{\sqrt{2}} (|\varphi_L\rangle + |\varphi_R\rangle)$.